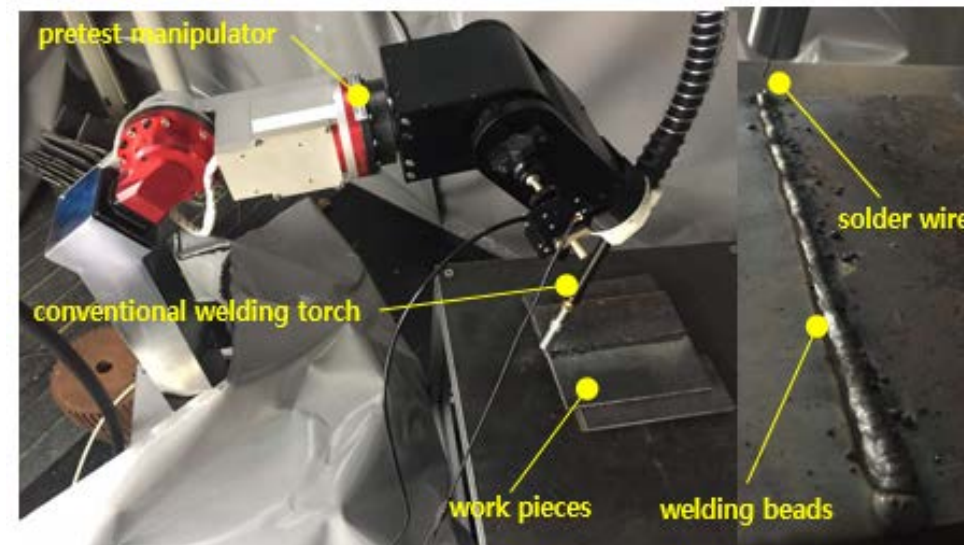
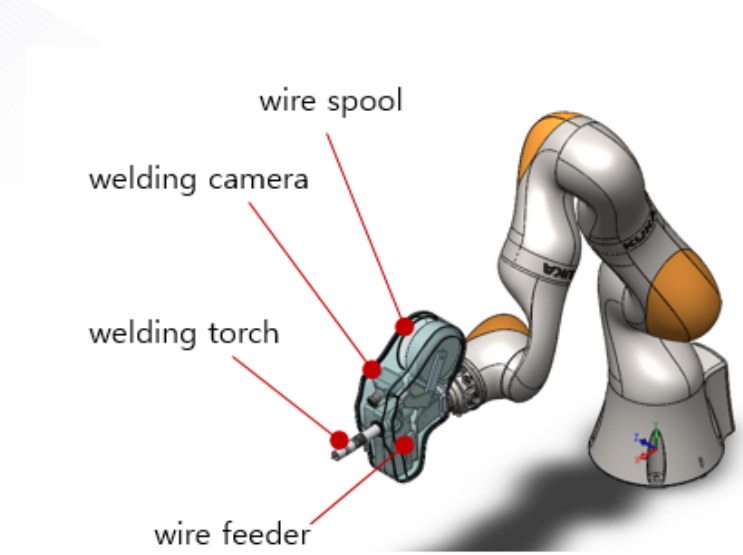


Remote MAG welding System

Dongseok Ryu @ KAERI



[global view] [local view]

Add Point	Edit Point	Delete Point
[P1] 1.10, 2.20, 3.30, 4.40, 5.50, 6.60		
[P2] 1.10, 2.20, 3.30, 4.40, 5.50, 6.60		
[P3] 1.10, 2.20, 3.30, 4.40, 5.50, 6.60		
[P4] 1.10, 2.20, 3.30, 4.40, 5.50, 6.60		
[P5] 1.10, 2.20, 3.30, 4.40, 5.50, 6.60		
[P6]		
[P7]		
[P8]		
[P9]		
[P10]		

Manipulator control

	Actual	Desired	
pose X :			< >
pose Y :			< >
pose Z :			< >
rot R :			< >
rot P :			< >
rot Y :			< >

GO

prec: Intensity S: 108000 Stop capture

Tool Select Mode Select Dry Run

확인 취소

[trajectory management]

[manipulator control]

[real time intervention]

